



1. Introduction

Steel moment-resisting frames (MRFs) are extensively used for low-to-medium rise building structures. To ensure that the life-safety objective is achieved, MRFs are usually designed to experience large inelastic deformation to dissipate the energy of the input strong earthquakes [1]. However, recent earthquake attacks exposed deficiencies of conventional MRFs which underwent large inelastic deformations. These large inelastic deformations can result in substantial post-earthquake residual drifts [2]. Thus, researchers have developed innovative MRFs to achieve improved seismic behaviour. For example, innovative steel MRFs equipped with various energy dissipation components were investigated. Ke and colleagues [3-6] have explored the effectiveness of energy dissipation bays for enhancing the seismic behaviour of a high strength steels (HSS) frame. The enhanced seismic behaviour of the structure was verified by experimental investigations [3,4]. It is worth noting that the post-earthquake residual drift is a critical index to determine whether a building should be repaired or demolished. McCormick's research [7] showed that if the post-earthquake residual interstorey drifts of the structure exceed 0.5%, the structure may need to be demolished. Therefore, it is of great significance to mitigate the post-earthquake residual deformation of a structure, and applying the "self-centring technology" based on post-tensioning connections or Shape Memory Alloys (SMA) [7-9] in steel MRFs becomes a promising solution.

In light of the above, this study explores the seismic behaviour of an innovative structure, i.e. steel MRFs with HSS members and self-centring energy dissipation bays, namely the HSSF-SCEDB structure. In particular, it is proposed that smart connections equipped with Shape Memory Alloy are installed in the self-centring energy dissipation bays (SCEDBs), and SCEDBs may dissipate energy and realise excellent self-centring behaviour. The primary objective of this conference paper is to explore the seismic behaviour of HSSF-SCEDB structure. The seismic behaviour of a prototype HSSF-SCEDB is examined by cyclic pushover analysis and nonlinear response history analyses (NL-RHAs). The critical engineering demand indexes such as maximum interstorey drift (MID), post-earthquake residual interstorey drifts (RID), plastic energy dissipation and peak absolute floor acceleration (PA) are gathered from the analysis database and examined in detail.

2. Prototype buildings

2.1 Basic information about the prototype structure

To explore the seismic behaviour of the HSSF-SCEDB system, a proof-of-concept study is initiated recently. The basic information about the prototype structure is shown in this section. The prototype structure includes three-stories and four-bays. The three-storey prototype structure is designed according to the Chinese seismic design provisions [10]. The structure is designed as an office building and located on sites with stiff soil. This focus of the current conference paper study is the 2-D frame that represents the east-west (EW) direction of the structure. In the EW direction, the HSSF-SCEDB is composed of four bays, including two HSS main frames and two SCEDB bays, as shown in Fig. 1. Two self-centring energy dissipation bays (SCEDBs) are located at the external bays of the structures, and the SMA connections are installed in the SCEDBs. The column bases are fixed. In the horizontal direction, the dimension of the self-centring energy dissipation bays and the HSS frame is 1.5 m along with 6.0 m, respectively. A SCEDB is composed of two HSS columns and beams connecting the columns, and self-centring connections with the super-elastic SMA bolts are used to connect the beams with the columns (Fig. 1b).



To explore the seismic behaviour of the HSSF-SCEDB system, both nonlinear static procedures (pushover analysis) and nonlinear response history analysis (NL-RHA) are performed, and the P- Δ effect is considered. The cyclic pushover analysis is achieved by using the invariant lateral force pattern corresponding to the fundamental vibration mode. In order to obtain the lateral load vector, the frequency analysis should be carried out first. Table 2 shows the elastic dynamic properties of the prototype structure. “Equation” option in ABAQUS [12] is used to apply the invariant lateral load distribution.

The NL-RHAs are applied to examining the seismic response of prototype structure subjected to the ground motions. In this study, twenty ground motions are selected from the SAC project (i.e. coded from LA01 to LA20) as excitations to analyses of the prototype structure [15]. They are recorded as ground motions on sites of stiff soil with 10% probability of exceedance in fifty (50) years. Fig. 3 shows the acceleration spectra with the damping ratio at 5%. In NL-RHAs, a damping ratio of 5% [16] is used to develop the Rayleigh damping matrix for the first two vibration modes. To capture the residual interstorey drift responses of the prototype structure after a ground motion, additional analysis time (100s) were added following the input earthquake.

Table 2 – Dynamic properties of the prototype HSSF-SCEDBs.

Structure	Property (unit)	1st Mode	2nd.Mode
3-storey system	Period (s)	0.70	0.17
	Modal effective mass (t)	179.54	19.22
	Modal participation factor	1.30	0.50
6-storey system (A) ($L_{SMA}=75$ mm)	Period (s)	1.67	0.54
	Modal effective mass (t)	466.10	77.20
	Modal participation factor	1.37	0.53
6-storey system (B) ($L_{SMA}=150$ mm)	Period (s)	1.90	0.62
	Modal effective mass (t)	469.21	71.99
	Modal participation factor	1.36	0.52

3.2 Case study and cyclic pushover responses

The seismic behaviour of HSSF-SCEDB under a ground motion (LA08) is examined through a case study. The displacement (u_g), velocity (v_g) and acceleration (a_g) time-history responses of the ground motion (LA08) are shown in Fig. 4. It is found that the ground motion has large acceleration and velocity pulses but with insignificant permanent displacement, and the dominant pulse occurs at 15-20s.

Fig. 5 shows the responses of the interstorey drift and absolute floor acceleration of each floor of the prototype structure under the ground motion (LA08). Each floor of the prototype structure generally exhibits a similar peak interstorey drift and absolute floor acceleration, which occurs at the dominant seismic velocity pulse (i.e. 15-20s). As shown in Fig. 5a, after undergoing peak interstorey drift, the prototype structure immediately rebounded with a smaller reverse peak interstorey drift, which is due to the unique flag-shaped hysteretic responses of the HSSF-SCEDB. In addition, each floor of the prototype structure oscillates near the zero-drift line with the insignificant interstorey residual drifts. Fig. 5b shows the responses of the absolute floor acceleration of the prototype structure. The prototype structure shows large absolute acceleration response, the peak absolute acceleration value achieves 0.75g, which is almost twice as much as the PGA (0.42g). Thus, the HSSF-SCEDB structure may significantly amplify the ground acceleration, and may cause economic losses associated with the damage to the non-structural component.

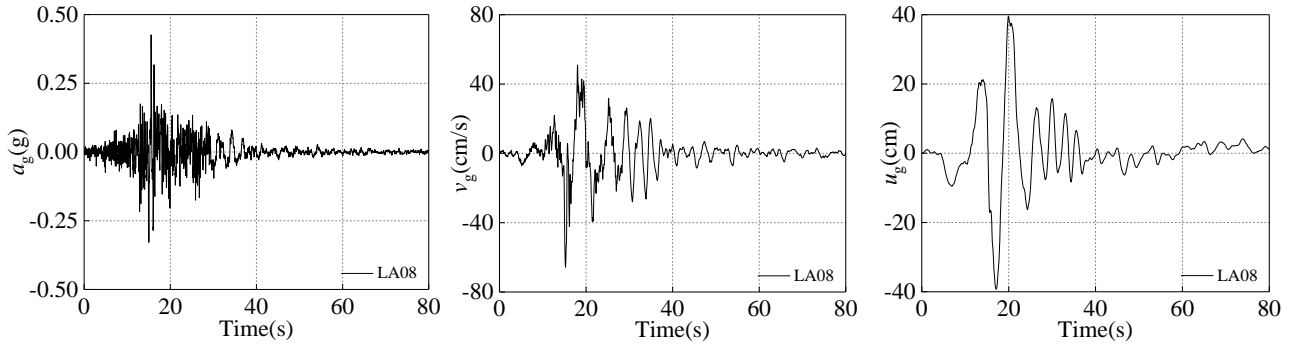


Fig. 4 – Time-history responses of the ground motions (LA08).

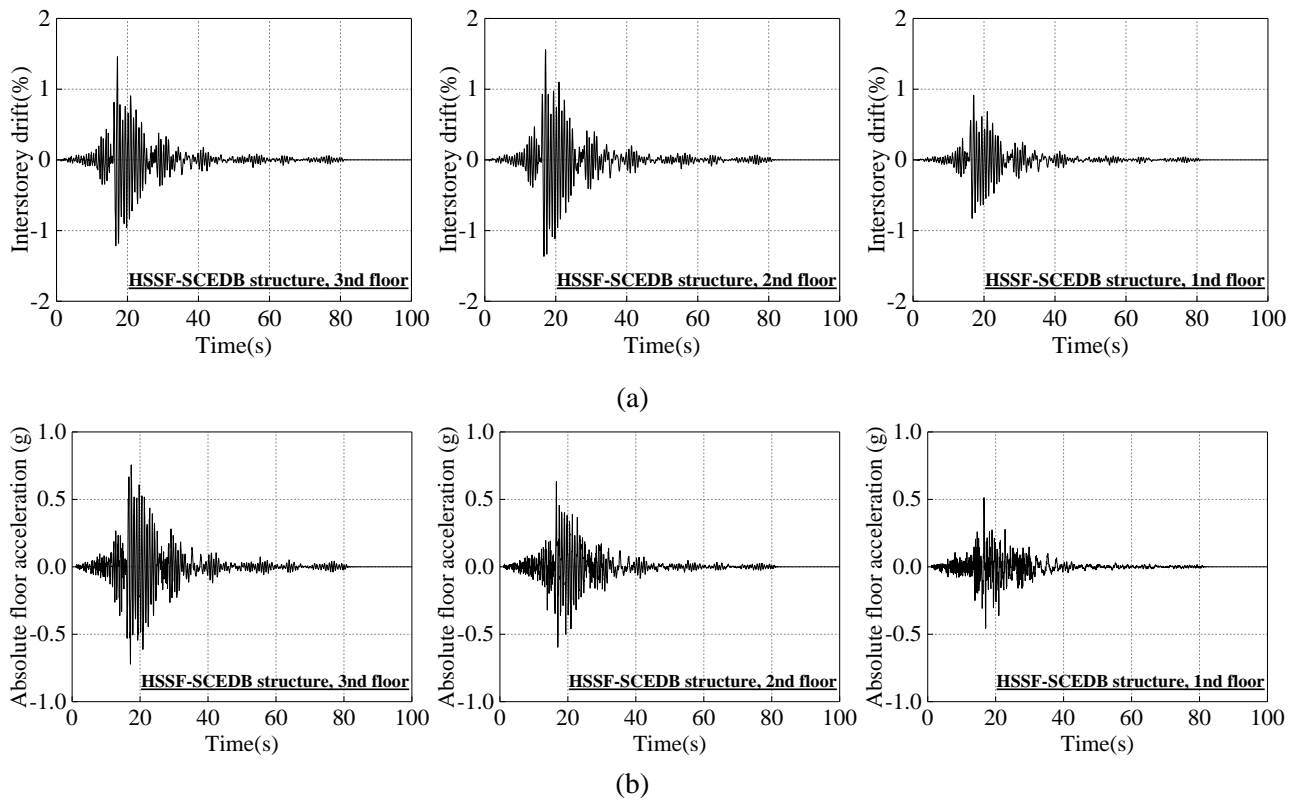


Fig. 5 – Case study: (a) interstorey drift responses, (b) acceleration responses.

The cyclic pushover response of the prototype structure (up to the maximum roof drift of 4%) is shown in Fig. 6. The cyclic pushover response of the prototype structure shows a typical flag-shape hysteretic response, excellent self-centring behaviour and good energy dissipation capacity. With the increase of the loading drift, stiffness hardening is also observed due to material properties of SMAs (i.e. Martensite hardening).

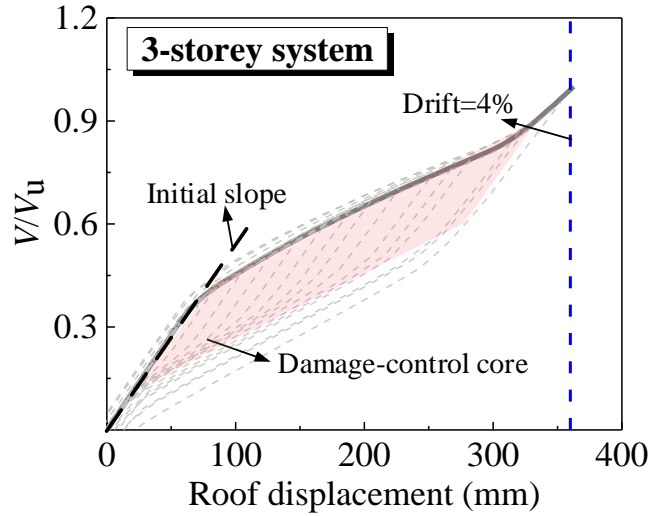


Fig. 6 – Cyclic pushover response of prototype structures.

3.3 Seismic response of prototype structure under ground motions

Fig. 7 shows the responses of the maximum interstorey drifts (MID), residual interstorey drifts (RID) and peak absolute floor acceleration (PA) of the prototype structure under each individual ground motion. The median, mean and 84th percentile values of the demand indexes are also illustrated. The prototype structure undergoes the most intense earthquake responses when subjected to ground motion LA14 and LA16. According to Fig. 3, At the first mode period of the prototype structure (i.e 0.7s), the two ground motions (LA14 and LA16) have the most significant spectral accelerations. Thus, it appears that the deformation responses of the prototype structure are associated with the spectral acceleration of the first mode period.

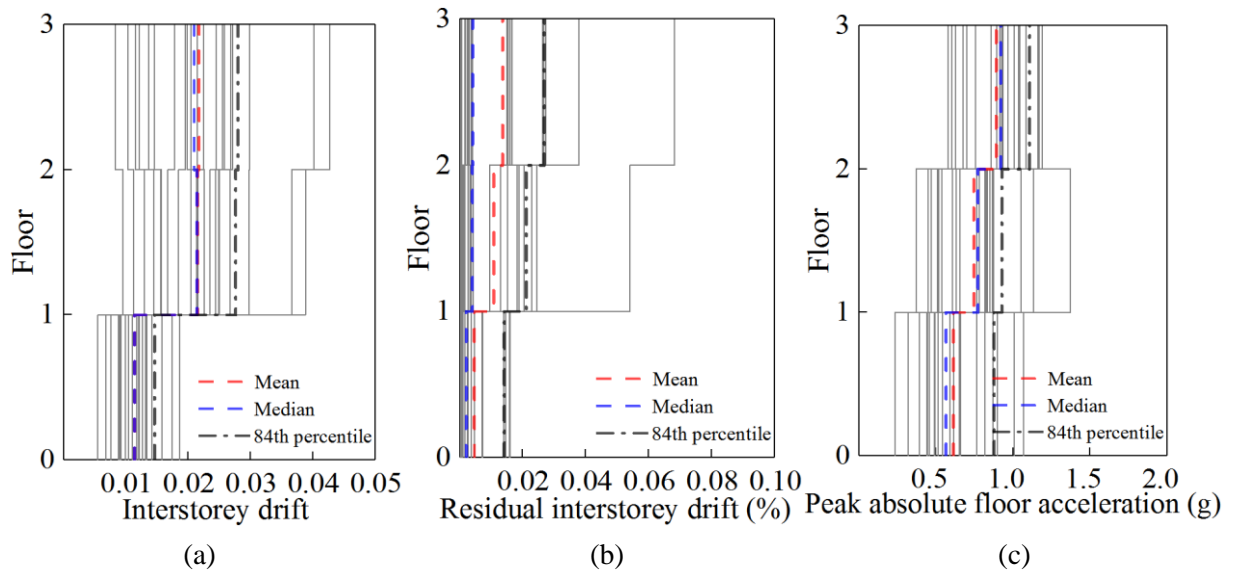


Fig. 7 – Seismic responses: (a) Maximum interstorey drifts, (b) Residual interstorey drifts, (c) Peak absolute floor acceleration.

Although the MID responses are generally above 2%, the RID responses are insignificant. In particular, the maximum RID responses of the prototype structure are below 0.1%, and the average RID response is generally below 0.03%. In contrast, the RID responses of conventional steel moment resisting frames (MRFs) under ground motions may exceed 0.5% [17]. Thus, the excellent self-centring behaviour of HSSF-SCEDB is confirmed.

